



## 1. Introduction

Triacs are used to control AC mains loads. In most applications, the triac will dissipate enough power to make thermal considerations necessary. The size of heatsink must be calculated and the maximum junction temperature must be predicted. Such thermal design procedures must be followed if long-term reliability of the application is to be assured. **Thermal design and analysis form an essential part of the design and development process.**

The thermal design requires several stages of calculation involving power, thermal resistance and temperature rise. This Application Note introduces those calculations. Worked examples are included, the data for which is derived from the customer's application or the triac's data sheet.

## 2. Calculating triac power

Triac power dissipation is influenced by the load current. Full sine wave current (full wave conduction) is assumed, since it presents the worst-case condition of maximum triac power dissipation. It also makes for the easiest calculations. If calculations are required for half wave conduction (e.g. for an SCR), please refer to the following subsection: "How to calculate  $I_{T(RMS)}$  and  $I_{T(AVE)}$  for half wave conduction".

Equation (1)

$$P = V_0 \times I_{T(AVE)} + R_S \times I_{T(RMS)}^2$$

$P$  – triac power dissipation (W).

$V_0$  – triac knee voltage (V).

This value is given in WeEn data sheets on the  $I_T / V_T$  curve. If the value is not available, it can be obtained from the  $I_T / V_T$  curve as described in the following subsection: "How to calculate  $V_0$  and  $R_S$ ".

$I_{T(AVE)}$  – average load current (A). This value is calculated from the application's RMS load current using equation 2. (This assumes full wave conduction and sinusoidal load current, which will give worst-case power dissipation.)

Equation (2)

$$I_{T(AVE)} = \frac{2 \times \sqrt{2} \times I_{T(RMS)}^2}{\pi}$$

$R_s$  – triac slope resistance ( $\Omega$ ). This value is given in WeEn data sheets on the  $I_T / V_T$  curve. If the value is not available separately, it can be obtained from the  $I_T / V_T$  curve as described in the following subsection: “How to calculate  $V_0$  and  $R_s$ ”.

$I_{T(RMS)}$  – RMS load current (A). This value is measured in the application.

## 2.1 How to calculate $I_{T(RMS)}$ and $I_{T(AVE)}$ for half wave conduction

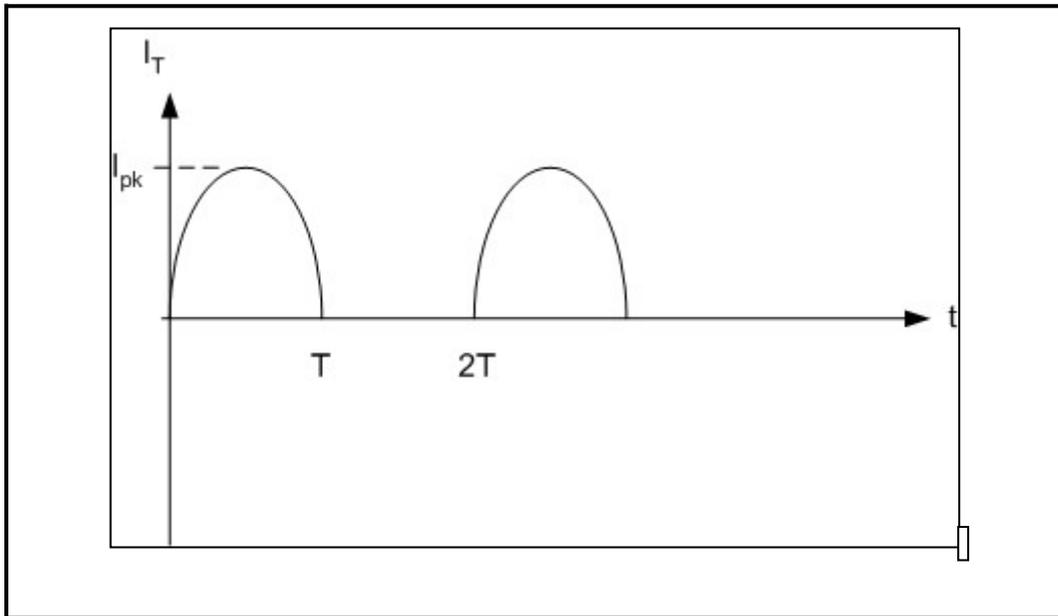


Fig. 1 Half wave conduction – e.g. SCR at full power on AC mains.

Equations (3), (4) and (5)

$$I_{T(AVE)} = \frac{2 \times I_{pk} \times T}{\pi \times 2T} = \frac{I_{pk}}{\pi}$$

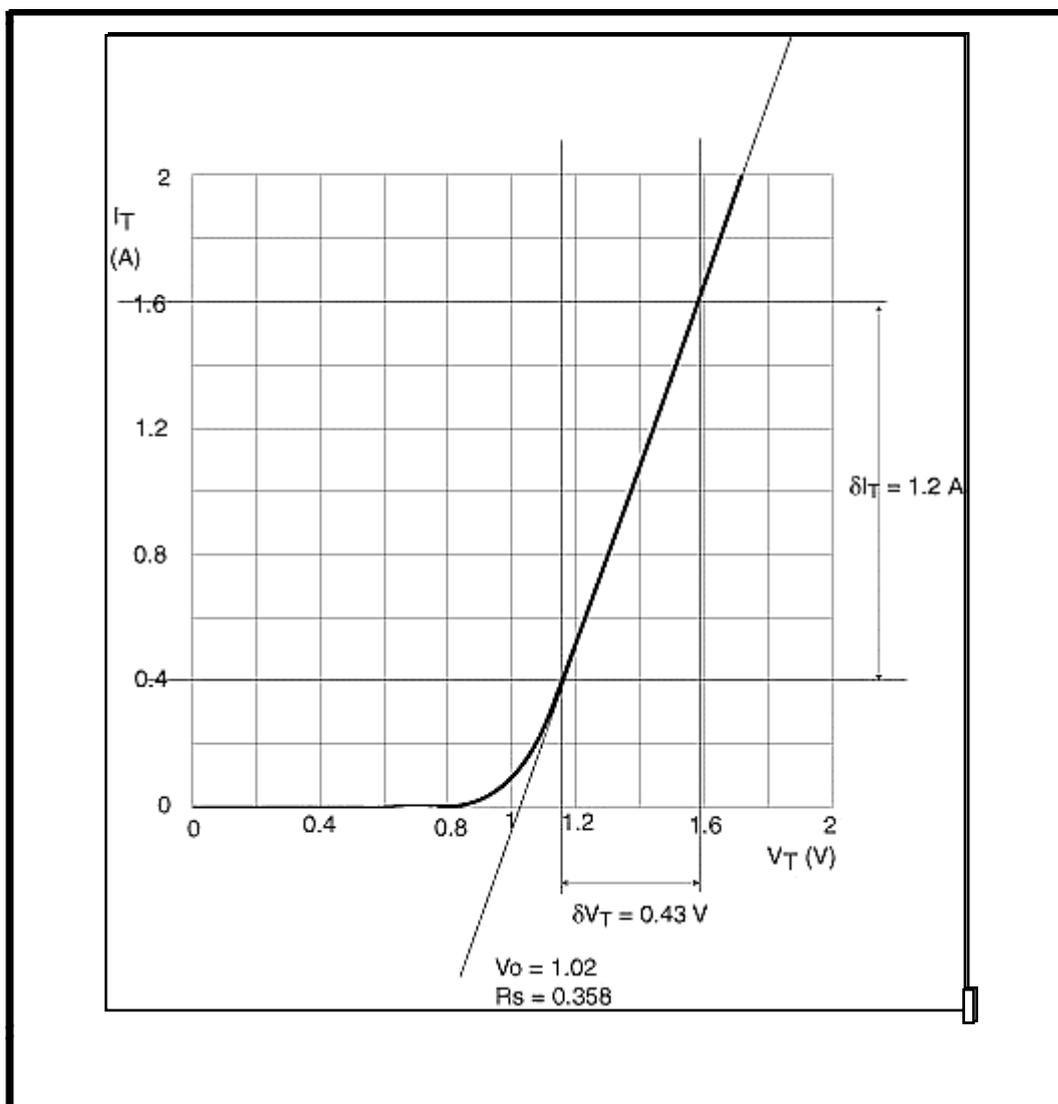
$$I_{T(RMS)}^2 = \frac{I_{pk}^2 \times T}{2 \times 2T} = \frac{I_{pk}^2}{4}$$

$$\text{Therefore, } I_{T(RMS)} = \frac{I_{pk}}{2}$$

## 2.2 How to calculate $V_0$ and $R_s$

If values for  $V_0$  and  $R_s$  are not given in the data sheet, you will have to generate the data yourself. This is easy to do as follows: -

1. Use an enlarged copy of the  $I_T / V_T$  curve.
2. Draw a tangent to the max  $V_T @ T_{j(max)}$  curve at the rated current of the triac.
3. The point where the tangent crosses the  $V_T$  axis gives  $V_0$ .
4. The slope of the tangent  $V_T / I_T$  gives  $R_s$ .



**Fig. 2 Using the tangent method to calculate  $V_0$  and  $R_s$ .**

**(Note: For worst-case conditions and a hot triac, always use the “max  $V_T @ T_{j(max)}$ ” curve.)**

### 3. Calculating $T_{j(\max)}$

$T_{j(\max)}$  is influenced by ambient temperature, triac power dissipation and the thermal resistance between junction and ambient. For this Application Note, only the steady state condition will be considered. [In the short-term transient condition, transient thermal impedance ( $Z_{th}$ ) applies. This will always be lower than the steady-state thermal resistance ( $R_{th}$ ). The transient condition is a lot more complicated and beyond the scope of this guide.

$$T_j = T_a + P \times R_{th(j-a)}$$

$T_j$  – junction temperature (°C).

$T_a$  – ambient temperature (°C).

$P$  – triac power dissipation (W).

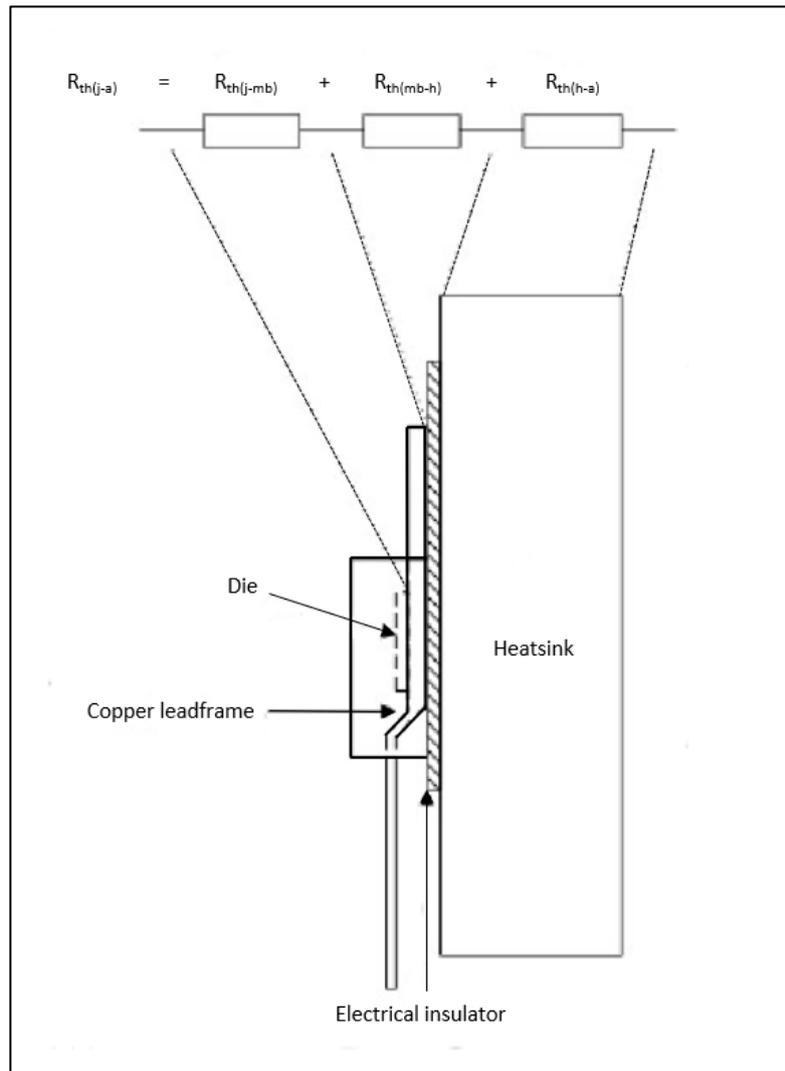
$R_{th(j-a)}$  – junction-to-ambient thermal resistance (°C/W).

#### 3.1 Analysis of $R_{th(j-a)}$

Thermal resistance is like electrical resistance in that the total resistance can be broken down into several smaller resistances in series. For the most popular package (TO220),  $R_{th(j-a)}$  is composed of the following resistances:

$$R_{th(j-a)} = R_{th(j-mb)} + R_{th(mb-h)} + R_{th(h-a)}$$

Figure 3 shows thermal resistance broken down in pictorial form.



**Fig. 3 Composition of thermal resistance for the T0220 package**

$R_{th(j-mb)}$  – junction-to-mounting base thermal resistance ( $^{\circ}\text{C}/\text{W}$ ). This is fixed and governed by the device as it is influenced by die size. Refer to the relevant data sheet for the exact value.

$R_{th(mb-h)}$  – mounting base-to-heatsink thermal resistance ( $^{\circ}\text{C}/\text{W}$ ). This is controlled by the equipment manufacturer because it is governed by the mounting method – e.g. with or without thermal grease, screw or clip mounted, insulating pad material, etc.

$R_{th(h-a)}$  – heatsink-to-ambient thermal resistance ( $^{\circ}\text{C}/\text{W}$ ). This is governed by the application and is under the sole control of the equipment designer.

Please note that there are some important caveats in the way the thermal resistance is specified because it depends on the package type and the practicality of isolating a metallic thermal reference point.

1. For plastic packages without a metal mounting base,  $R_{th(j-mb)} + R_{th(mb-h)}$  is replaced by a single spec of  $R_{th(j-h)}$ , since the heatsink is the nearest metallic reference point.
2. For low power plastic packages where a heatsink would not be used, only  $R_{th(j-lead)}$  is specified, since the leads are the nearest metallic reference point. Most of the heat would be conducted through the leads to the PCB, with a little radiated directly from the package to ambient. For these packages we would specify a total  $R_{th(j-a)}$  with certain assumptions about how the device is mounted on the PCB, which represent typical use.
3. For some surface mount packages without a mounting base (mb) but a “*solder point*” instead,  $R_{th(j-mb)}$  is replaced by  $R_{th(j-sp)}$ . For these packages we would specify a total  $R_{th(j-a)}$  when the device is mounted onto a PCB with a specified area of copper.

**Table 1** lists some WeEn triac packages and the means of specifying their thermal resistance. Thermal resistance values are given wherever they are fixed by the package type or mounting method. If the thermal resistance is influenced by the triac die, the correct value can be obtained from the data sheet.

Package type	Thermal resistance specification	Thermal resistance (°C/W)
T092	$R_{th(j-lead)}$	60
	$R_{th(j-a)}$ (PCB mounted, lead length = 4 mm)	150
T0220	$R_{th(j-mb)}$	See Datasheet
	$R_{th(mb-h)}$ (clip, with grease, no insulator)	0.3
	$R_{th(mb-h)}$ (screw, with grease, no insulator)	0.5
	$R_{th(mb-h)}$ (clip, no grease, no insulator)	1.4
	$R_{th(mb-h)}$ (screw, no grease, no insulator)	1.4
	$R_{th(mb-h)}$ (clip, with grease, 0.1 mm mica insulator)	2.2
	$R_{th(mb-h)}$ (clip, with grease, 0.25 mm alumina insulator)	0.8
	$R_{th(mb-h)}$ (screw, with grease, 0.05 mm mica insulator)	1.6
	$R_{th(mb-h)}$ (screw, no grease, 0.05 mm mica insulator)	4.5
	$R_{th(j-a)}$ (free air without heatsink)	60
SOT82	$R_{th(j-mb)}$	See Datasheet
	$R_{th(mb-h)}$ (clip, with grease, no insulator)	0.4
	$R_{th(mb-h)}$ (clip, no grease, no insulator)	2.0
	$R_{th(mb-h)}$ (clip, with grease, 0.1 mm mica insulator)	2.0
	$R_{th(mb-h)}$ (clip, no grease, 0.1 mm mica insulator)	5.0
	$R_{th(j-a)}$ (free air without heatsink)	100
T0220F (SOT186A)	$R_{th(j-h)}$ (with grease)	See Datasheet
	$R_{th(j-h)}$ (no grease)	See Datasheet
	$R_{th(j-a)}$ (free air without heatsink)	55
SOT223	$R_{th(j-sp)}$	See Datasheet
	$R_{th(j-a)}$ (free air, minimum pad area, FR4 PCB)	150 typ
T0263 (D <sup>2</sup> PAK)	$R_{th(j-mb)}$	See Datasheet
	$R_{th(j-a)}$ (free air, minimum pad area, FR4 PCB)	55 typ
T0252 (DPAK)	$R_{th(j-mb)}$	See Datasheet
	$R_{th(j-a)}$ (free air, minimum pad area, FR4 PCB)	75 typ

**Table 1: WeEn triac packages and their thermal resistance specifications.**

## 4. Worked examples

### 4.1 Vacuum cleaner

A triac is used in a phase control circuit to control the speed of a vacuum cleaner motor. Confirm by calculating for worst-case conditions that the triac's  $T_{j(max)}$  of 125 °C will not be exceeded.

Application data: -

Motor power = 1kW max.

Mains supply = 230V RMS.

$$\therefore I_{T(RMS)} = \frac{P}{V} = \frac{1000}{230} = 4.35A$$

The triac is clamped to the die-cast metal housing of the turbine, without thermal grease, for heatsinking purposes. Therefore, an insulated triac package is required.

Maximum heatsink temperature is 80 °C.

Calculations: -

A “Hi-Com” triac of 12A is recommended to cope with the inrush current, which can be very high in this application. The suggested triac is BTA312X-600B, which uses the isolated TO220F package, suitable for heatsinking directly to the turbine housing. Its  $I_{GT}$  of 50mA is well matched to the drive circuit.

Using equation 2,

$$I_{T(AVE)} = \frac{2 \times \sqrt{2} \times I_{T(RMS)}}{\pi} = \frac{2 \times \sqrt{2} \times 4.35}{\pi} = 3.92A$$

From the data sheet,  $V_0 = 1.164V$  and  $R_s = 0.027\Omega$ .

Using equation 1,

$$P = V_0 \times I_{T(AVE)} + R_s \times I_{T(RMS)}^2 = 1.164 \times 3.92 + 0.027 \times 4.35^2 = 5.07W$$

Using equation 7,

$$R_{th(j-a)} = R_{th(j-mb)} + R_{th(mb-h)} + R_{th(h-a)}$$

From the data sheet,  $R_{th(j-h)} = 5.5 \text{ }^\circ\text{C/W}$  without heatsink compound.

$R_{th(h-a)}$  can be regarded as zero, since the turbine housing acts as an infinite heatsink with a maximum temperature fixed at  $80 \text{ }^\circ\text{C}$  under worst-case airflow conditions.

Therefore,  $R_{th(j-a)}$  is  $5.5 \text{ }^\circ\text{C/W}$ .

Using equation 6,

$$T_j = T_a + P \times R_{th(j-a)} = 80 + 5.07 \times 5.5 = 108 \text{ }^\circ\text{C}$$

This is below  $T_{j(max)}$  of  $125 \text{ }^\circ\text{C}$ , therefore acceptable.

## 4.2 Refrigerator compressor

A triac is used in an electronic thermostat that controls the ON-OFF switching of a refrigerator compressor. What maximum heatsink thermal resistance can keep the junction temperature of the triac within its  $T_{j(max)}$  of  $125 \text{ }^\circ\text{C}$ ?

Application information: -

Steady state motor current = 1.4A RMS.

Maximum inrush current = 17A peak in the first half cycle.

Mains supply = 230V RMS.

A surface mounted triac is required for direct soldering to the controller PCB.

Maximum ambient temperature is  $40 \text{ }^\circ\text{C}$ .

The triac gate is triggered from a microcontroller with 20mA current sink capability.

Calculations: -

A "Hi-Com" triac of 8A is recommended to cope with the inrush current. The suggested triac is BTA208S-600E, which uses the TO252 (DPAK) package. Its  $I_{GT}$  of 10 mA is well matched to the drive capability of the microcontroller.

Using equation 2,

$$I_{T(AVE)} = \frac{2 \times \sqrt{2} \times I_{T(RMS)}}{\pi} = \frac{2 \times \sqrt{2} \times 1.4}{\pi} = 1.26A$$

From the data sheet,  $V_0 = 1.264 \text{ V}$  and  $R_s = 0.0378 \text{ } \Omega$ .

Using equation 1,

$$P = V_0 \times I_{T(AVE)} + R_S \times I_{T(RMS)}^2 = 1.264 \times 1.26 + 0.0378 \times 1.44^2 = 1.67W$$

Using equation 6,

$$T_j = T_a + P \times R_{th(j-a)}$$

We already know that  $T_a = 40^\circ C$  and  $P = 1.67W$ , and in this case,  $T_j = T_{j(max)} = 125^\circ C$ .

Rearranging the equation gives: -

$$R_{th(j-a)} = \frac{T_j - T_a}{P} = \frac{125 - 40}{1.67} = 51^\circ C/W$$

Using equation 7,

$$R_{th(j-a)} = R_{th(j-mb)} + R_{th(mb-h)} + R_{th(h-a)}$$

From the data sheet,  $R_{th(j-mb)} = 2^\circ C/W$ . We need to find  $R_{th(mb-a)}$ .

Rearranging the equation gives: -

$$R_{th(mb-a)} = R_{th(j-a)} - R_{th(j-mb)} = 51 - 2 = 49^\circ C/W$$

This is effectively the “heatsink” thermal resistance, since the PCB is the heatsink in this case.

As an approximate guide, this thermal resistance can be obtained with a copper pad area of  $500 \text{ mm}^2$  (refer to WeEn Application Note, WAN003, “Surface mounted triacs and thyristors”).

Please note that the actual thermal resistance will be reduced by other, non-dissipating components in close proximity to the triac, while it will be increased by any components that dissipate power in the presence of the triac. It is essential therefore to measure the prototype to discover the true thermal performance.

### 4.3 Top-loading (Vertical Axis) washing machine

This machine uses a reversing induction motor that's controlled by two triacs.

Will the triacs'  $T_{j(\max)}$  of 125 °C be exceeded if they are operated without a heatsink?

Application data: -

Full load motor power = 300W.

Mains supply = 230V RMS.

$$\therefore I_{T(RMS)} = \frac{P}{V} = \frac{300}{230} = 1.3A$$

Isolated triac package is required.

Maximum ambient temperature is 40 °C.

Calculations: -

This application will benefit from 1000 V triacs to withstand the high AC mains voltage that the motor imposes across them. A three-quadrant design is mandatory for maximum immunity to false triggering. The BTA208X-1000C or BTA208B-1000C are possible options. These are 8 A, 1000 V, Hi-Com triacs with  $I_{GT}$  of 35 mA. They use the TO220F "all plastic", "full pack" insulated package and TO263 (D<sup>2</sup>PAK) surface mount package respectively.

Using equation 2,

$$I_{T(AVE)} = \frac{2 \times \sqrt{2} \times I_{T(RMS)}}{\pi} = \frac{2 \times \sqrt{2} \times 1.3}{\pi} = 1.17A$$

From the data sheet,  $V_0 = 1.216$  V and  $R_s = 0.0416$  Ω.

Using equation 1,

$$P = V_0 \times I_{T(AVE)} + R_s \times I_{T(RMS)}^2 = 1.216 \times 1.17 + 0.0416 \times 1.3^2 = 1.49W$$

Using equation 6,

$$T_j = T_a + P \times R_{th(j-a)}$$

We already know that  $T_a = 40$  °C and  $P = 1.49W$ .

From the data sheet,  $R_{th(j-a)}$  for the TO220F package in free air is 55 °C/W.

$$\therefore T_j = 40 + 1.49 \times 55 = 122^\circ\text{C}$$

This is below the  $T_{j\text{max}}$  of  $125^\circ\text{C}$ . Therefore, the triacs can be operated without heatsinks.

## 4.4 Power tool

A heavy-duty electric drill uses a universal (brush) motor whose speed is controlled by a half-wave phase control circuit. Calculate the maximum power dissipation in the Silicon Controlled Rectifier and calculate the heatsink thermal resistance required to maintain the junction temperature below  $T_{j(\text{max})}$ .

Application data: -

Full load peak motor current = 5A.

A surface mounted triac is required for mounting within the trigger switch.

Maximum ambient temperature is  $50^\circ\text{C}$ .

The SCR is air-cooled from the motor cooling fan.

Calculations: -

The BTH151S-650R is recommended. Its 12 Amp RMS rating and ruggedized internal construction provide a high repetitive surge guarantee for the best reliability in repetitive overload situations. It uses the TO252 (DPAK) package.

Using equation 3,

$$I_{T(AVE)} = \frac{I_{pk}}{\pi} = \frac{5}{\pi} = 1.59\text{A}$$

Using equation 5,

$$\therefore I_{T(RMS)} = \frac{I_{pk}}{2} = \frac{5}{2} = 2.5\text{A}$$

From the data sheet,  $V_0 = 1.06\text{V}$  and  $R_s = 0.0304\Omega$ .

Using equation 1,

$$P = V_0 \times I_{T(AVE)} + R_s \times I_{T(RMS)}^2 = 1.06 \times 1.59 + 0.0304 \times 2.5^2 = 1.88\text{W}$$

Using equation 6,

$$T_j = T_a + P \times R_{th(j-a)}$$

We already know that  $T_a = 50^\circ\text{C}$  and  $P = 1.88\text{W}$ , and in this case,  $T_j = T_{j(\text{max})} = 125^\circ\text{C}$ .

Rearranging the equation gives: -

$$R_{th(j-a)} = \frac{T_j - T_a}{P} = \frac{125 - 50}{1.88} = 39.9^\circ\text{C/W}$$

Using equation 7,

$$R_{th(j-a)} = R_{th(j-mb)} + R_{th(mb-h)} + R_{th(h-a)}$$

From the data sheet,  $R_{th(j-mb)} = 1.8^\circ\text{C/W}$ . We need to find  $R_{th(mb-a)}$ .

Rearranging the equation gives: -

$$R_{th(mb-a)} = R_{th(j-a)} - R_{th(j-mb)} = 39.9 - 1.8 = 38.1^\circ\text{C/W}$$

This “heatsink” thermal resistance covers the steady-state condition and is easily achievable with a small degree of airflow through the switch module.

## Revision history

Rev	Date	Description
v.1	20050810	initial version
v.2	20190501	new company update
v.3	20190718	format update
v.4	20190805	worked examples update

## Contact information

For more information and sales office addresses please visit: <http://www.ween-semi.com>

## Legal information

### Definitions

**Draft** — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. WeEn Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

### Disclaimers

**Limited warranty and liability** — Information in this document is believed to be accurate and reliable. However, WeEn Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. WeEn Semiconductors takes no responsibility for the content in this document if provided by an information source outside of WeEn Semiconductors.

In no event shall WeEn Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, WeEn Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the *Terms and conditions of commercial sale* of WeEn Semiconductors.

**Right to make changes** — WeEn Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

**Suitability for use** — WeEn Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an WeEn Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. WeEn Semiconductors and its suppliers accept no liability for inclusion and/or use of WeEn Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

**Applications** — Applications that are described herein for any of these products are for illustrative purposes only. WeEn Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using WeEn Semiconductors products, and WeEn Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the WeEn Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third-party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

WeEn Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third-party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using WeEn

Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third-party customer(s). WeEn does not accept any liability in this respect.

**Export control** — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

**Evaluation products** — This product is provided on an "as is" and "with all faults" basis for evaluation purposes only. WeEn Semiconductors, its affiliates and their suppliers expressly disclaim all warranties, whether express, implied or statutory, including but not limited to the implied warranties of non-infringement, merchantability and fitness for a particular purpose. The entire risk as to the quality, or arising out of the use or performance, of this product remains with customer.

In no event shall WeEn Semiconductors, its affiliates or their suppliers be liable to customer for any special, indirect, consequential, punitive or incidental damages (including without limitation damages for loss of business, business interruption, loss of use, loss of data or information, and the like) arising out the use of or inability to use the product, whether or not based on tort (including negligence), strict liability, breach of contract, breach of warranty or any other theory, even if advised of the possibility of such damages.

Notwithstanding any damages that customer might incur for any reason whatsoever (including without limitation, all damages referenced above and all direct or general damages), the entire liability of WeEn Semiconductors, its affiliates and their suppliers and customer's exclusive remedy for all of the foregoing shall be limited to actual damages incurred by customer based on reasonable reliance up to the greater of the amount actually paid by customer for the product or five dollars (US\$5.00). The foregoing limitations, exclusions and disclaimers shall apply to the maximum extent permitted by applicable law, even if any remedy fails of its essential purpose.

**Translations** — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

### Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owner

## Contents

<b>1. Introduction</b> .....	<b>1</b>
<b>2. Calculating triac power</b> .....	<b>1</b>
<b>2.1 How to calculate <math>I_{T(RMS)}</math> and <math>I_{T(AVE)}</math> for half wave conduction</b> .....	<b>2</b>
2.2 How to calculate $V_o$ and $R_s$ .....	3
<b>3. Calculating <math>T_{Jmax}</math></b> .....	<b>4</b>
3.1 Analysis of $R_{thj-a}$ .....	4
<b>4. Worked examples</b> .....	<b>8</b>
4.1 Vacuum cleaner .....	8
4. Refrigerator compressor.....	9
4.3 Top-loading (Vertical Axis) washing machine.....	11
4.4 Power tool.....	12
<b>Revision history and contact information</b> .....	<b>15</b>
<b>Legal information</b> .....	<b>15</b>
Definitions .....	15
Disclaimers .....	15
Trademarks .....	15
<b>Contents</b> .....	<b>16</b>

Please be aware that important notices concerning this document and the product(s) described herein have been included in section 'Legal information'.

© WeEn 2019.

All rights reserved

For more information, please visit: <http://www.ween-semi.com>

Date of release: 18 July 2019

Document identifier: WAN004